

#### The tkLayout package

Status and outlook

13 May 2013

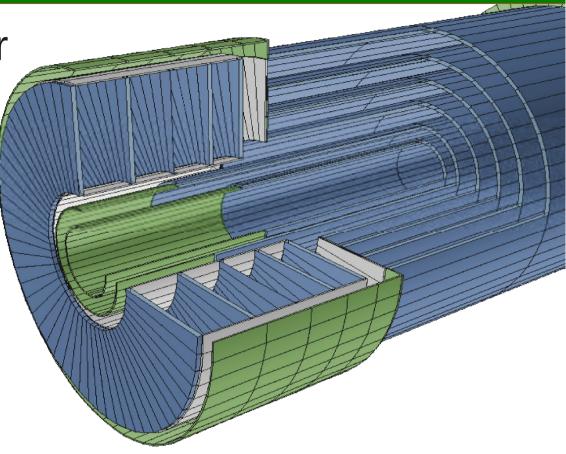
Giovanni Bianchi - CERN

# tkLayout

- Standalone tool to model tracker layouts
- **3d model** of the tracker from simple config files
- Material model
- Computes performance estimates (tracking performance, module pT resolution)
- Includes **parametrizations** (power dissipation, occupancy, ...)
- Through the produced performance figures it enables:
  - Rapid prototyping of a tracker layout
  - Optimization of a layout
  - Quantitative comparisons between layouts
- Exports geometry to CMSSW

#### Tracker modelling

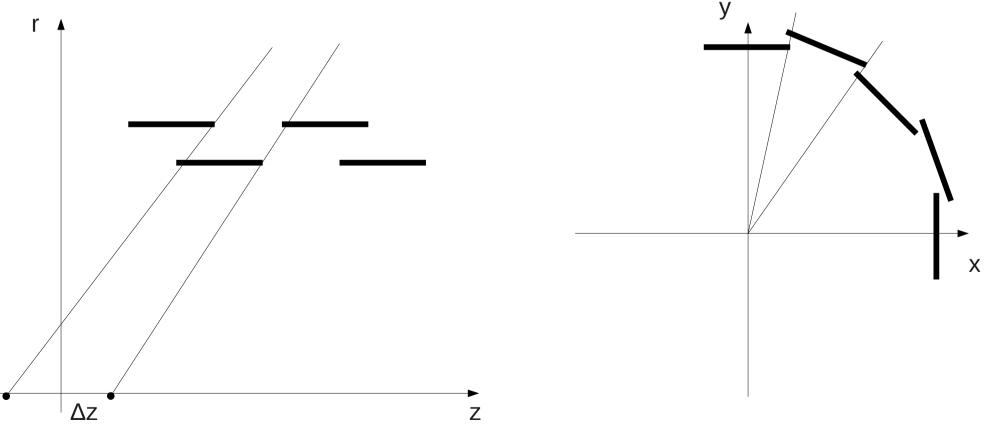
- 3d model of the tracker
  - Modules
  - Supports
  - Services



• To keep the computation and configuration simple, tkLayout makes some assumptions fitting the future CMS tracker (modules organized in layers / rings, services routed with predefined criteria, ...)

#### Tracker modelling

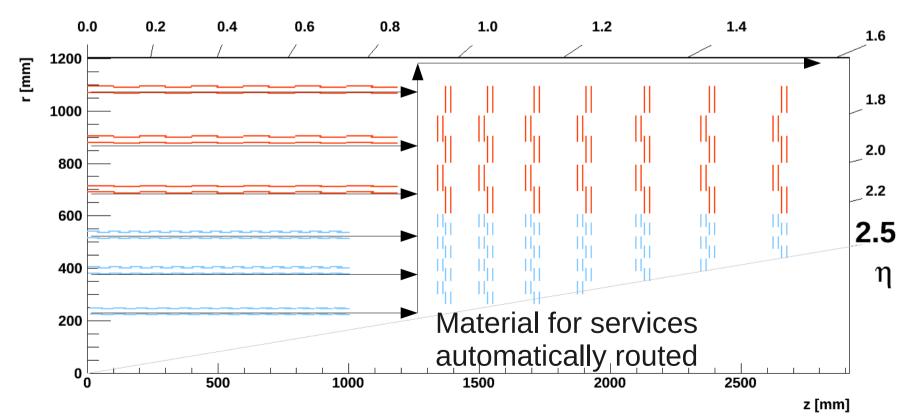
• Modules automatically placed so that the tracker is hermetic



Similar considerations can be made for the endcap

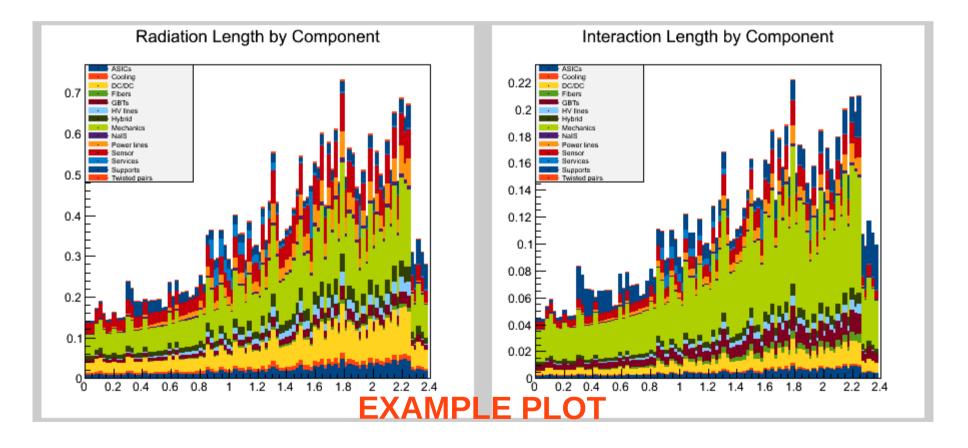
#### Materials

- Materials are added to the geometry
  - Can be local to active elements (components)
  - Can be services
  - Can be support structures



#### Materials

• Radiation and interaction lengths



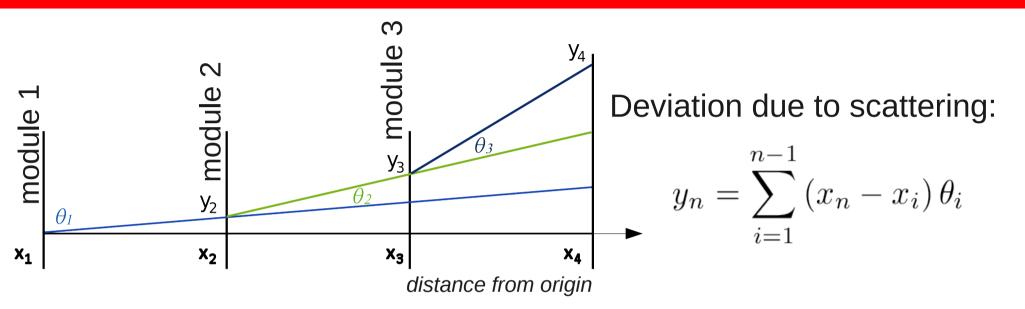
#### **Performance Estimates**

- Tracking performance
- Module pT resolution

### Tracking performance

- A-priori error estimate:
  - No Monte Carlo
  - No fitting
- Ingredients:
  - Error propagation
  - Sensor resolution (measurement error)
  - Multiple scattering (treated as a correlated measurement error)

### **Tracking performance**



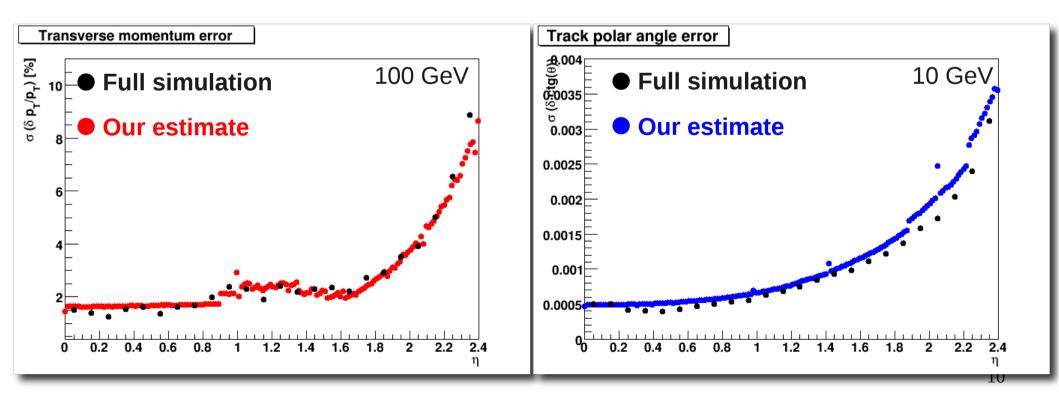
Covariance matrix of the measured hit coordinates:

$$\boldsymbol{\sigma_n^2} = \frac{p^2}{12}$$
  
$$\boldsymbol{\sigma_{n,m}} = \langle y_n y_m \rangle = \sum_{i=1}^{n-1} (x_m - x_i) (x_n - x_i) \langle \theta_i^2 \rangle$$

Method validated against the full CMSSW simulation

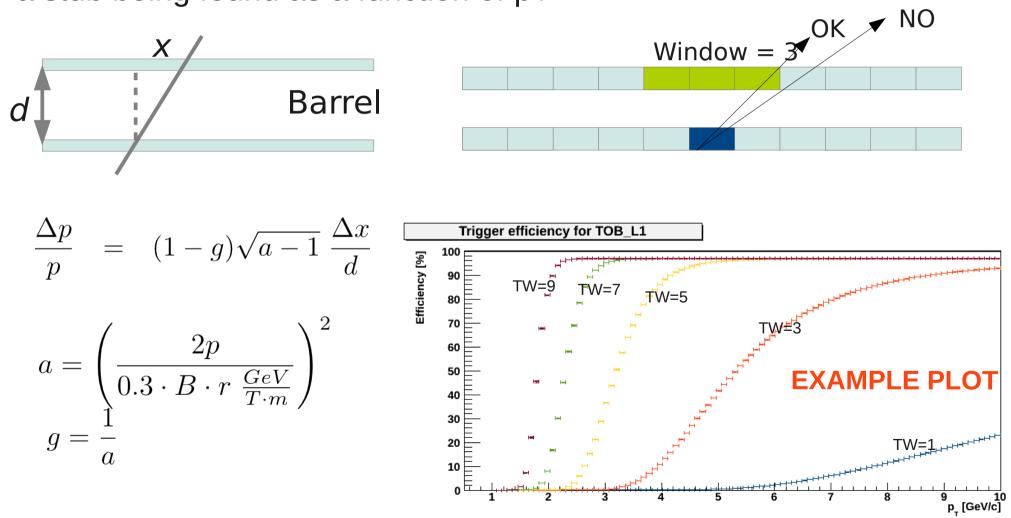
#### **Tracking performance**

 Method validated by modelling the current CMS tracker and comparing the results with CMSSW Full Sim



#### Module pT resolution

- For the tuning of sensor spacing and trigger windows
- Given spacing and window it is possible to compute the probability of a stub being found as a function of pT

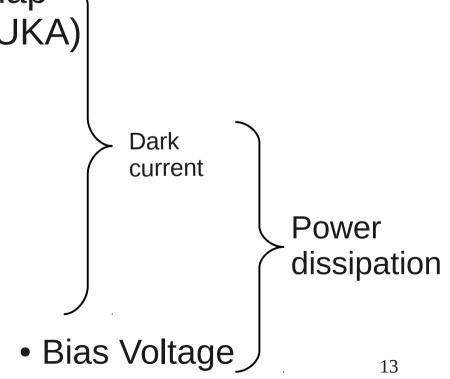


#### Parametrizations

- Power dissipation after irradiation
- Occupancy and stub rate
- Multiple trigger towers
- Bandwidth
- Cost

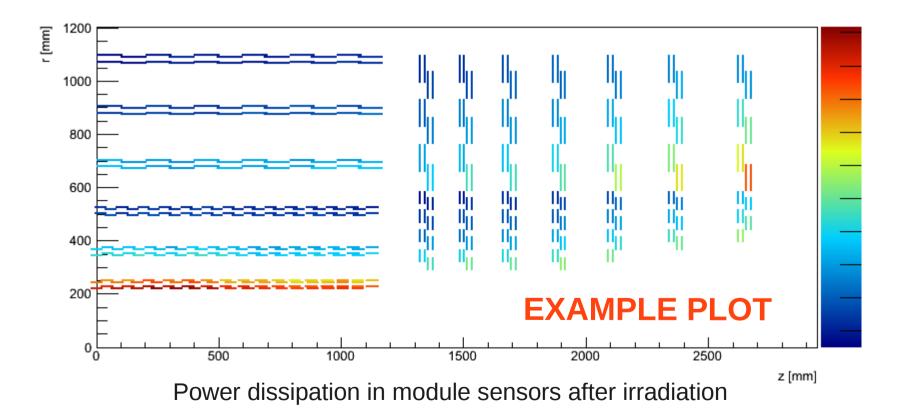
### **Power dissipation**

- Estimate of the power dissipation of modules (sensors + chip) after irradiation
- Parameters:
  - 1 MeV eq neutron fluence map scaled to  $\int L = 3000 \text{ fb-1}$  (FLUKA)
  - Sensor location
  - Sensor thickness
  - Sensor temp
  - Annealing temp
  - α parameter



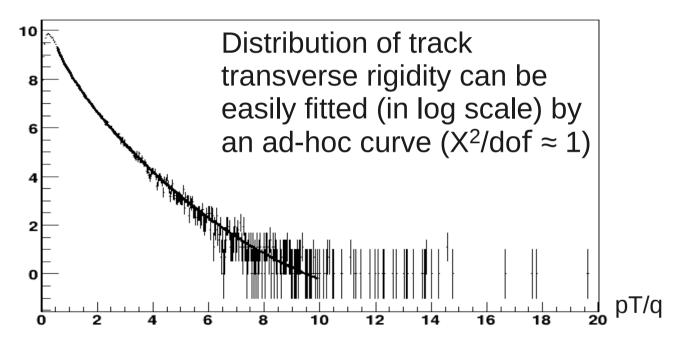
#### **Power dissipation**

• Estimate of the power dissipation of modules after irradiation



#### Occupancy and stub rate

 Stubs from high-pT particles, come from fitted distribution of primaries (Pythia)



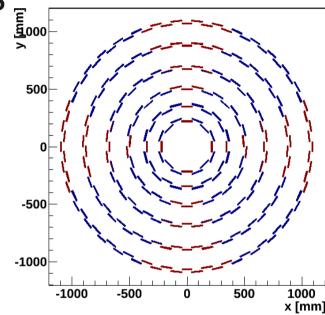
- Stubs from low-pT particles are derived by pure combinatorial of hits
  - Occupancy model comes from the current CMS tracker

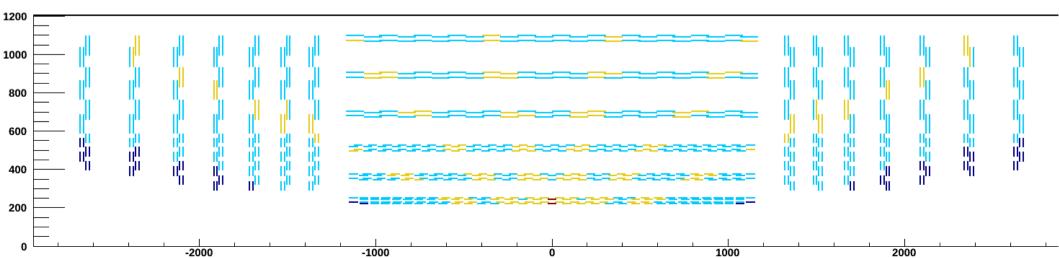
#### Occupancy and stub rate

- Figures of merit provided:
  - Trigger efficiency
  - High pT particle frequency
    - Theoretical no. of stubs from high pT hits (per event)
  - Trigger frequency true
    - High pT particle frequency \* trigger efficiency
  - Trigger frequency fake
    - no. of stubs from low pT hits making the cut (per event)
  - Trigger purity
    - Stubs from high-Pt / total stubs formed

# Multiple trigger towers

- Assumes independent trigger towers.
  - Overlap between sectors
- Produces:
  - Sectoring of the detector based on num phi/eta sectors, min accepted pT
  - Estimate of # connections, stub rate, bandwidth per TT





#### Export to CMSSW

- Export of geometries generated with tkLayout into CMSSW via XML files
- The latest CMSSW release uses tkLayoutgenerated geometries
- It works but there are still some minor issues:
  - Some manual editing of the XML files still needed to make them CMSSW-compatible
  - Anyway, as of now, importing a geometry into CMSSW takes just 2 hours

### Conclusions

- The suite of estimates and parametrizations offered by tkLayout make it an invaluable tool to help in the choice of a future CMS tracker
- tkLayout is being extensively used for:
  - The modelling of different tracker layout families and variations
  - Their optimization and tuning
  - Quantitative comparisons of their performance
- The next presentation by S. Mersi will show some of the studies performed with tkLayout



#### Backup slides

# Module pT resolution

- Hypothesis for the calculation
  - "High" pT particles (pT>0.5 GeV) are mainly primaries (as extracted from a MB Monte-Carlo Generator)
  - Low pT particles are much more abundant and can be extracted from the predicted occupancy

### Occupancy and stub rate

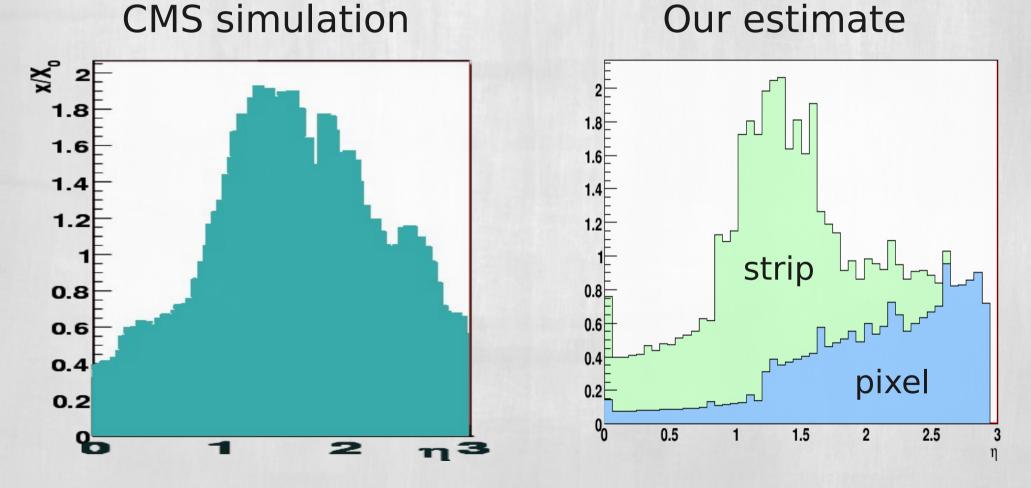
 Stubs from low-pT particles are derived by pure combinatorial of hits

> Window = 3For each hit on Each paired strip in window prob = occupancy one sensor  $N \times OCC \times W \times OCC$ 23

# Material - everything

# =Distribution of material inside the tracking volume

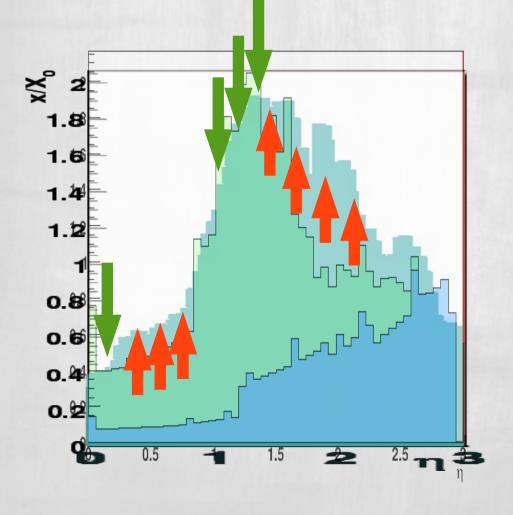
24



Differences are expected and understood

# Material - everything

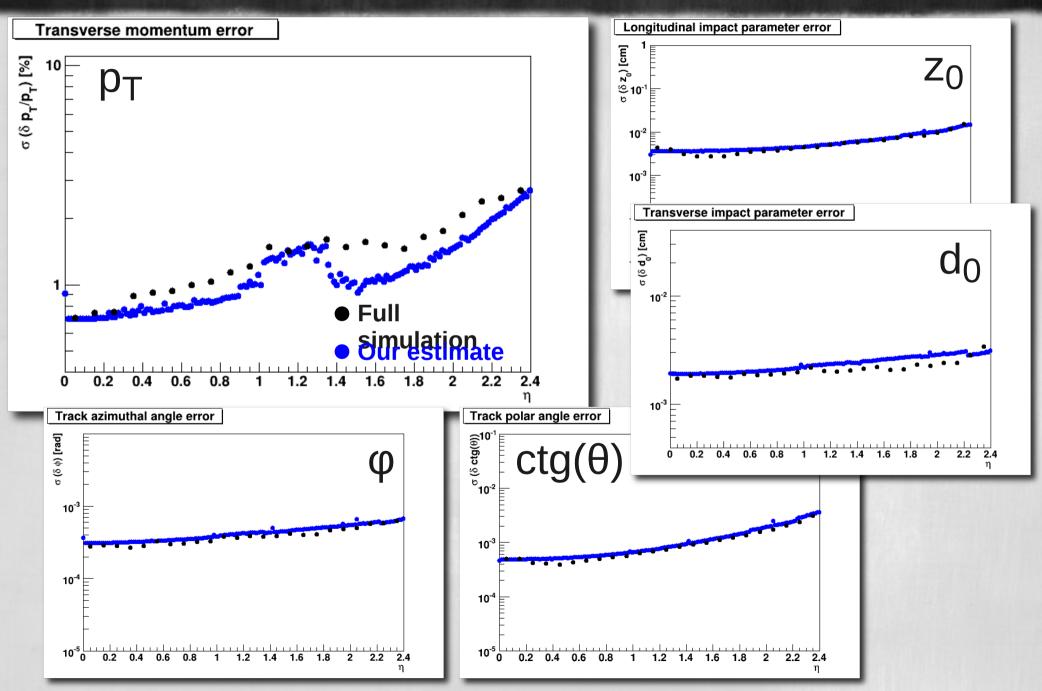
=Distribution of material inside the tracking volume



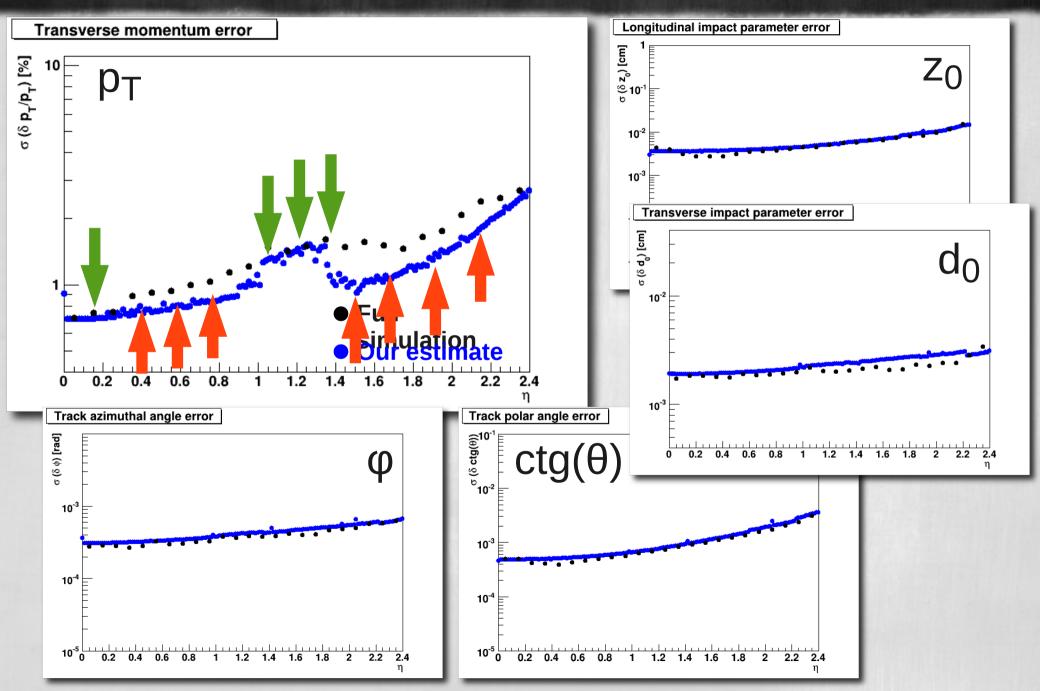
Material budget was correctly reproduced on the material peak and z=0

Differences are more marked in other areas (this is expected and understood)

# Performance @ 10 GeV/c<sup>26</sup>



# Performance @ 10 GeV/c<sup>27</sup>



#### Performance @ LUU

